A Cost-Efficient System for Detecting an Intentional Electromagnetic Interference (IEMI) Attack

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Abstract—This paper describes a cost-efficient Intentional EMI Detection system and gives a brief overview of the identification and location system being developed as part of the STRUCTURES project.

Index Terms — Intentional Electromagnetic Interference (IEMI), Electromagnetic Threat, RF Sensor, HPM Detection, HPM Protection

I. INTRODUCTION

The possible use of Intentional Electromagnetic Interference (IEMI) to disrupt critical infrastructure is becoming a significant concern [1]. One aspect of this threat is detecting the cause of a system failure. A failure due to IEMI may be blamed on faulty hardware or software, and much time and money may be wasted on searching for the cause, particularly if the failure is intermittent. It is therefore beneficial to consider how IEMI attacks may be detected. A number of IEMI detector systems have been developed previously such as those in references [2] and [3] which can detect IEMI. Although reference [4] describes a system that can determine the direction to the IEMI source, we have not been able to find references describing practical systems capable of determining the complete location of the source. In this paper we describe a low cost detection system being developed as part of the STRUCTURES programme. The STRUCTURES programme is one of several EU funded research programmes evaluating the effects of IEMI on critical infrastructure, including protection and detection. A complementary identification and location system is also being designed and a brief description is included in this paper for comparative purposes.

II. DETECTOR DESIRABLES

The three most important requirements for the detection system are the ability to detect an IEMI attack and generate an alarm, to send the received data for logging and post-processing, and to be cost-efficient. Additional features, such as locating and/or identifying the source of the attack, require designing a significantly more complex system, which is thus likely to be more expensive. Within the STRUCTURES project we are developing both, low-cost and high-performance detectors outlined in this paper.

A. Detection of threat

Clearly the first desirable property of a detector is that it can successfully detect the presence of an IEMI threat. False alarms should also be minimized. A field detector must have some means of discriminating between IEMI threats and other intentional or accidental sources such as mobile phones and electrostatic discharge. For simple detectors the discrimination between threat and other fields might be largely based on the level, though this can also be aided by ensuring that the detector is located away from expected transmitters such as mobile phones. A more complex system might be able to discriminate on the basis of frequency content and/or the time domain waveform. Similarly, a conducted interference detector must be able to differentiate between “normal” levels of transient and noise on a wire and that introduced by IEMI.

Sources are available at ever increasing frequencies but their complexity increases with frequency. Although the majority of available sources operate below 3 GHz [7], detection at higher frequencies is desirable to allow for future developments.

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B. Communication and logging

In order to allow notification of a threat and subsequent analysis (forensics) of the time, duration and number of attacks, some mechanism is required for the data from a number of sensors to be communicated to a local or remote monitoring and logging system, to send alerts and alarm indications (e.g. to a security office).

C. Identification of threat

Identification of the type of interfering signal is desirable, partly to discriminate between signals that may not be IEMI, such as a nearby mobile phone, and partly to aid in tracking the source of interference. A simple system is likely to be able to determine simple waveform features such as whether the threat is CW, long or short pulse, but will be unable to observe details of very fast rise time or short pulses. A more sophisticated system may seek to determine frequency, rise-time, Pulse Repetition Frequency (PRF), etc. which can provide a picture of the source type in use.

D. Location of threat

Location of the source of the threat would enable action to be taken to identify and apprehend the perpetrators of the attack. It is possible that a simple system can give some indication of the location of a threat if a large number of detectors are used, simply by observing which detectors are triggered. A more complex system can use many techniques for direction finding, such as those based on antenna directivity, time difference of arrival, etc.

E. Cost

Any practical detector system will also have to be affordable. A low cost system may only be able to detect the presence of a possible threat, whereas a system capable of identifying and locating the threat is likely to be more expensive. Within the STRUCTURES project we are developing both low-cost and high performance detectors outlined in this paper.

III. A MODULAR DETECTOR SYSTEM

Here we propose a concept of a modular IEMI detector system and discuss how one such system can be upgraded to achieve localization and identification of an IEMI source.

A. Low cost detectors

Figure 1. shows the concept of the low-cost IEMI detection system being developed in the STRUCTURES project. Multiple sensors are coupled to a (protected) computer system for warning, logging and analysis. Optical fibre communications provide robust communications, though wireless or wired links may be desirable in some cases.
Figure 3. A low power, low cost detector

Figure 3. shows the radiated IEMI detector circuit driven by a source which represents a simple dipole model [9] (L1, R6, C4, C5). The shunt resistance R3, along with the antenna capacitance C4 define the low cut-off frequency. In this prototype, a positive peak detector (D1, C2, R10, & R4) with linear response was included with a buffer amplifier in order to allow observation of the detector output directly. A negative peak detector (D2, C3, & R5) feeds an inverting logarithmic amplifier which is to be used to drive a comparator and Analogue to Digital Converter (ADC) on the microcontroller. R12 provides a small bias to the diodes and ensures that the inverting op-amp has a small (~25 mV) positive output so that it functions adequately with a single supply rail. Figure 4. Shows the measured dynamic range of the fabricated detector.

The choice of detector RC time constant and operational amplifier determine both the time response and power consumption of the system. This should be matched to the sample rate of the ADC on the microcontroller which is of the order of 1 Msample/s. The LTC6264 amplifiers used here have a gain bandwidth product of 180 MHz and a 90V/µs slew rate with a quiescent current of less than 1 mA. This means that the buffer for the positive detector has a rise time of less than 20 ns. The rise time of the logarithmic amplifier depends on the signal amplitude and is significantly slower, around 2 µs. The performance is adequate to allow envelope capture of some pulsed waveforms. The decay time of the detector must also be slow enough for the ADC to capture amplitude information for shorter pulses and is currently set so the decay in one microsecond is about 10%.

Figure 4. Dynamic range of the low-cost detector

Figure 5. SPICE simulated time response of low-power, low-cost detector for sine wave input with detector capacitors set to 100 pF
The time response of a simple detector presents a challenge. The detector capacitance must be charged through the antenna capacitance. Also for smaller signals the diode conducts less and the rise time becomes longer. The prototype constructed uses a 100 pF capacitance which results in a detector rise-time of about 2 μs. This is compatible with the logarithmic amplifier performance as can be seen in Figure 5. The detector response can be improved by reduction in the detector capacitance as shown in Figure 6. However the logarithmic amplifier rise-time is limited for small signals as it is operating with a high gain. The buffer amplifier on the positive detector is able to follow the faster rise time and can be used to operate a comparator for short-pulse detection.

Kanda [9] showed that it is possible to achieve a flat frequency response over a broad bandwidth using a simple dipole antenna directly connected to a detector diode. This is due to the fact that the detector charges its output capacitor which eventually reverse-biases the diode so the antenna sees only the diode capacitance as its load. A dipole like antenna below resonance exhibits a purely capacitive impedance and this acts as a frequency independent potential divider with the diode capacitance. An 8 mm monopole has a quarter wave resonant frequency of approximately 9 GHz and Figure 7. shows the simulated frequency response of the monopole driving the capacitive load of the diode. A significant dip in antenna factor can be seen as the antenna passes through resonance.

Considering Figure 4. , if we assume that –40dBm in a 50Ω system is the limit of useable sensitivity for the detector, then this corresponds to a voltage of V=4.47 mV. For an 8 mm dipole with a 92 dB/m antenna factor, the corresponding minimum detectable field sensitivity is:

$$E_1 = V \cdot AF_1 = 178 \text{ V/m}$$  \hspace{1cm} (1)

Since the antenna forms a capacitive potential divider with the detector, the antenna factor can be controlled by modifying the antenna capacitance. Figure 8. shows an 8 mm high antenna with increased capacitance. We chose the shape as recent experience in designing a broadband antenna for reverberation chambers [11] shows that the taper at the base radiates well at frequencies above resonance and it suppresses the effect of the monopole resonance(s). It can be seen (Figure 9. ) that the increase in capacitance results in a substantial reduction of antenna factor. The reduced antenna factor of 55 dB results in an increased sensitivity of the detector such that the minimum detectable field is:

$$E_2 = V \cdot AF_2 = 2.5 \text{ V/m}$$  \hspace{1cm} (2)

Thus the sensitivity of the detector can be adjusted by choice of a suitable antenna capacitance.
B. Towards identification and location system

The described low cost detector system is able to determine basic waveform features, such as whether a threat is a continuous wave, long or short single pulse. However, it is not capable of distinguishing between and extracting the parameters of typical IEMI signal shapes, such as trains of sine wave pulses, damped sine pulses, and double-exponential pulses since IEMI signals are typically very short and exhibit very fast rise times. Proper identification of such signals can be accomplished in at least two ways: (i) by recording the waveform of the signal and analyzing its shape in the time or frequency domain offline, or (ii) by measuring and analyzing (algorithmically) the durations of the positive and negative half-pulses of the signal.

An identification and location system is also being developed as part of the STRUCTURES programme. Figure 10. shows a simplified block diagram of a more complex, and thus likely more expensive, system which can perform the detection of the attack, the localization of a radiated IEMI source, and the identification of the waveform of the malicious signal. The inputs to the system are signals collected from a set of spatially distributed field sensors. The main building blocks are signal detectors, needed to spot the attack, and the core signal-processing modules: waveshape identification and time-difference measurement modules. The signal selector block redirects one of the input signals to the output for visual analysis. The identification module measures and analyzes the duration of received signal half-pulses, to determine the approximate waveshape of the IEMI signal. The time-difference module detects the initial rising edge of the signals from the different sensors and measures the time delay between them. This module is crucial for calculating the location of the source using the Time Difference of Arrival Algorithm (TDoA). This algorithm is selected based on an analysis of the existing localization algorithms and the simulation results presented in [12].

IV. CONCLUSIONS

We have described the low cost, low power IEMI detector system, and given a brief overview of an identification and location system, being developed as part of the STRUCTURES Programme. This paper has focused on the design of the radiated IEMI detector for the low cost system. The conducted interference detector is yet to be developed.

REFERENCES